100

```
┌─────────────────┐     ┌─────────────┐     ┌─────────────────┐
│      OFDM       │     │             │     │      OFDM       │
│   TRANSMITTER   │────▶│   CHANNEL   │────▶│    RECEIVER     │
│       110       │     │     120     │     │       200       │
└─────────────────┘     └─────────────┘     └─────────────────┘
```

FIG. 1

FIG. 2

FIG. 3

410

OFDM RECEIVER

GIB
ALGORITHM

110

MAXIMUM
INDEX
LOCATOR
420

TIMING
ESTIMATES
(tim0, tim1, timfull)

FIG. 4

TIMING
FINITE
STATE
MACHINE
(FSM)

400

ACQTIME   ACQSTAT   TRACKTIME   TRACKSTAT

FIG. 5A

correlation of 184
samples spaced 2048
samples apart.
The process is
repeated to get 2232
sample correlation
output as shown below.

FIG. 5B

FIG. 5C

TIMING FSM
PROCESS - 600

IS TIM0 VARYING BY LESS
THAN GUARD INTERVAL
FROM FRAME TO FRAME
FOR PREDEFINED NUMBER
OF FRAMES (TACQLEN)?
610

NO

IS TIM1 VARYING BY LESS
THAN GUARD INTERVAL
FROM FRAME TO FRAME
FOR PREDEFINED NUMBER
OF FRAMES (TACQLEN)?
620

NO

YES

YES

TIM0 IS CORRECT TIMING;
ACQTIME = TIM0 – DESIREDPOS
ACQSTAT=1

630

TIM1 IS CORRECT TIMING;
ACQTIME = TIM1 – DESIREDPOS
ACQSTAT=1

640

DETERMINE TIMFULL
650

FIG. 6

WAIT FOR PREDEFINED NUMBER OF
FRAMES (INTER-MODE SETTLING PERIOD)
660

TRACKING
IS LOST;
SET
TRACKSTAT
= 0
690

USE TIMFULL FOR TRACKING
670

TRACKTIME = TIMFULL
– DESIREDPOS;
TRACKSTAT=1

685

IS TIMFULL VARYING BY
MORE THAN GUARD
INTERVAL FROM
DESIREDPOS FOR
PREDEFINED NUMBER OF
FRAMES (TACQLOSLEN)?
680

NO

YES

MODSC ALGORITHM - 700

FREQUENCY

FINITE

STATE ●

MACHINE

(FSM)

900

→ FACQSTAT ●

→ COURSE
FREQUENCY
OFFSET
ESTIMATE
(MULTIPLES
OF 4 KHZ)

C2ADJ

P2AV

COMPUTE
C2ADJ

770

COMPUTE
P2AV

775

MODIN

COMPUTE
AVG. POWER,
EXCLUDING
NULL 750

SELECT
NULL
SUB-CARRIER

755

SELECT
SUB-CARRIER
OF MINIMUM
POWER
760

COMPUTE
AVG. POWER,
EXCLUDING
MIN. POWER
CARRIER 765

FILTER
MODULE

735

SQUARED
ABSOLUTE
VALUE
MODULE
730

EXTRACT
MODULE

715

FIG. 7

0	1	18	2030	2047
zero carrier	positive carriers	unused carriers for MODSC	negative carriers	

FIG. 8

FREQUENCY FSM PROCESS 900

ARE BOTH
$[c2adj \le threshlt1]$ & $[p2av \ge threshgt1]$
TRUE?
905

NO

YES

HAS FREQUENCY BEEN CHANGED OR IS FACQSTAT = 1?
910

YES

NO

HAS MODIN BEEN THE SAME FOR PREDEFINED NUMBER OF FRAMES? 920

NO

YES

CHANGE FREQUENCY USING MODOUT;
OLDMODOUT=MODOUT
930

CALCULATE METDIFF FOR PREDEFINED NUMBER OF FRAMES
940

DID C2ADJ EXCEED THRESHOLD2 DURING PREDEFINED NUMBER OF FRAMES? 950

YES

NO

C2ADJFLAG=1
955

C2ADJFLAG=0
960

IS AVERAGE METDIFF > METDIFFTHRES AND C2ADJFLAG =1?
965

NO

YES

ACQUISITION IS DONE AND TRACKING BEGINS;
SET FACQSTAT=1
970

IS METDIFF > METDIFFTHRES AND MODIN ≠0 PREDEFINED NUMBER OF FRAMES? 975

NO

YES

ACQUISITION IS LOST; UNDO FREQ. CHANGE {set modout=oldmodout; oldmodout=0} 980

FIG. 9

IF AUTOMATIC GAIN CONTROL
PROCESS 1000

DID RF AGC 235 ADJUST THE
RF GAIN?
1010

YES

NO

ADJUST PREVIOUS IF GAIN
VALUE BY AN AMOUNT
OPPOSITE TO RF GAIN
ADJUSTMENT
1020

END

IS PRE-FFT THRESHOLD LESS
PRE-FFT MEASUREMENT >
DESIRED TOLERANCE?
1030

YES

NO

LOWER IF GAIN IN
STEPPED INCREMENTS
1040

END

IF GAIN ADJUSTMENT = MIN{PRE-FFT
THRESHOLD - PRE-FFT MEASUREMENT;
POST-FFT THRESHOLD - POST-FFT
MEASUREMENT} * LOOP GAIN CONSTANT
1050

END

FIG. 10

```
INPUT_PORT(1)  register float *Prepower;
INPUT_PORT(2)  register float *Postpower;
INPUT_PORT(3)  register float *RFgain;
OUTPUT_PORT(1) register float *Output;   /*IF AGC Gain in dB*/

BLOCKFACTOR long BlockFactor;

PARAMETER(1) float OutputIntervalWidth; /* 71 dB*/
PARAMETER(2) float SetPointdBPre;       /*42.2*/
PARAMETER(3) float SetPointdBPost;      /*32.2*/
PARAMETER(4) float Kagc;        /*0.25*/
PARAMETER(5) float PreDropdB;           /* 3.0*/
PARAMETER(6) long WaitTime;             /*8 OFDM Frames!!*/

STATE float oldoutput;
STATE float oldrfgain;
STATE long counter;

#include <math.h>

void init ofdmagccontrol2()
{
/* initialize Sum */
oldoutput = 0.0;
counter = WaitTime;
}

void ofdmagccontrol2()
{
register float dbinpre, dbinpost, err, rfgain, output;
float HalfInterval = (OutputIntervalWidth / 2.0);
```

FIG. 11A

```
LOOP(BlockFactor)

        printf("------------------IFbeg--------\n");
        dbinpre = *Prepower++; dbinpost = *Postpower++;
        rfgain = *RFgain++;

        printf("prepower = %f, post = %f, rfgain = %f\n", dbinpre, dbinpost, rfgain);
        if((rfgain-oldrfgain)!=0.0)
                {
                output = oldoutput -(rfgain-oldrfgain);
                printf("ifgain = -rfdiff = %f, oldrfgain = %f\n", output, oldrfgain);
                }
        else if ((SetPointdBPre-PreDropdB-dbinpre <=0.0)&& (counter >= WaitTime))
                {
                output = oldoutput -(PreDropdB+2.0);
                printf("ifgain = due to Pre  = %f\n", -PreDropdB);
                counter=0;
                }
        else

                {
                counter++;
                if(SetPointdBPre-dbinpre < SetPointdBPost-dbinpost)
                        err = SetPointdBPre - dbinpre;
                else
                        err = SetPointdBPost-dbinpost;
                err = Kagc*err;
                output = oldoutput+err;
                printf("output = %f\n", output);
                }

        if(output>=HalfInterval)
                output  = HalfInterval;
        else if (output<=-HalfInterval)
                output = -HalfInterval;
        else
                output = output;

        *Output++ = output;
        oldrfgain = rfgain;
        oldoutput = output;
        printf("------------------IFend--------\n");
ENDLOOP
}
```

FIG. 11B